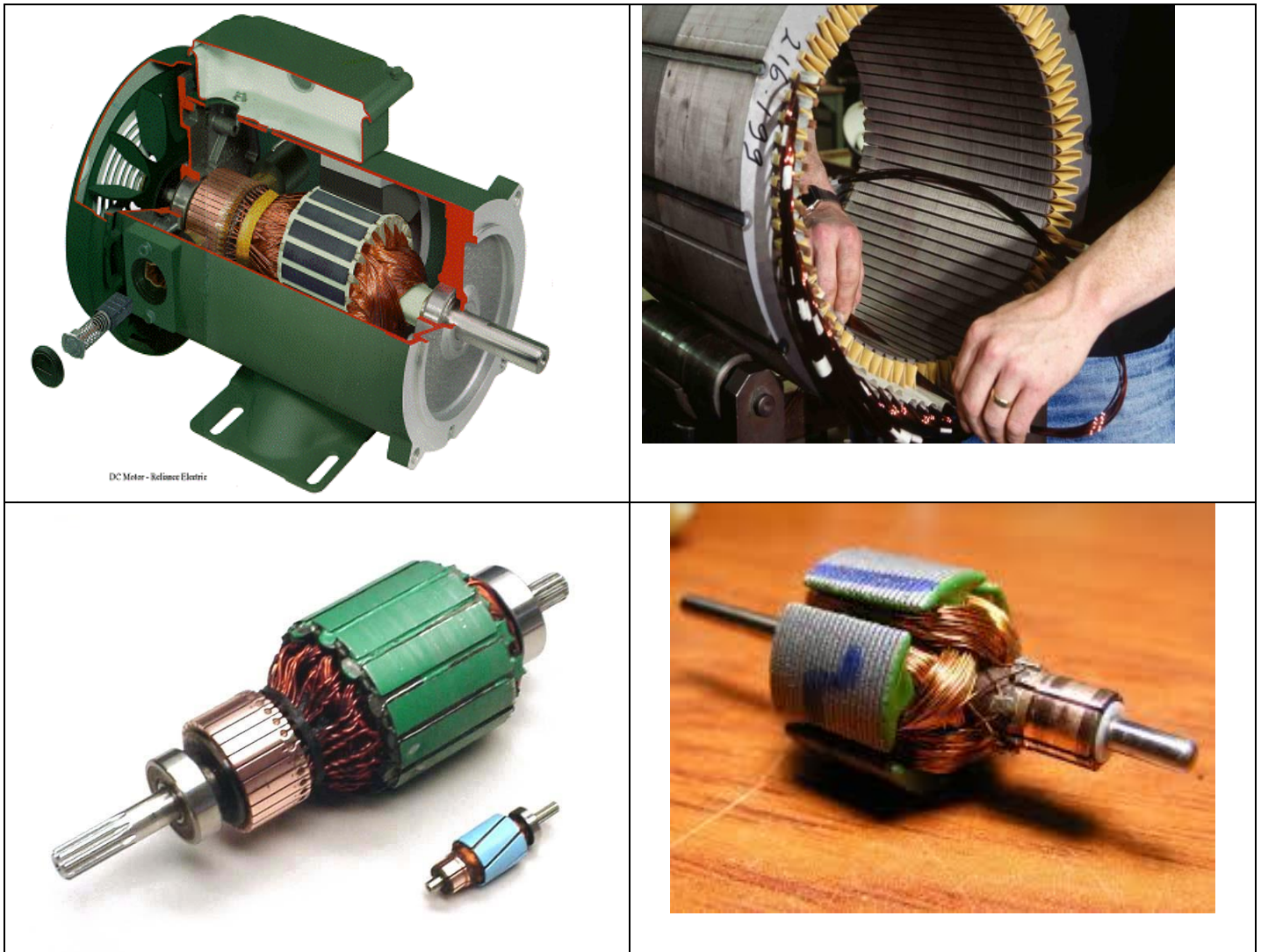


DC Motor Design

(© Dr. R. C. Goel & Nafees Ahmed)



By



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References:

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DC Machine Design

OUTPUT EQUATION: -

It gives the relationship between electrical rating and physical dimensions (Quantities)

Output of a DC machine

$$Q = E_g \times I_a \times 10^{-3} \quad KW \quad \text{-----(1)}$$

Where

$$E_g = \text{Generated voltage} = \frac{PN\phi Z}{60A}$$

$$\phi = \bar{B} \times \tau_p \times L = \bar{B} \times \frac{\Pi D}{P} \times L = \text{Flux per pole}$$

P = No of poles

N = Speed in RPM

Z = Total no of armature conductors

I_a = Armature current

$$I_z = \text{Current per conductor} = \frac{I_a}{A}$$

$$\text{Total Ampere Conductors} = Z I_z$$

Total Ampere conductors is known as total electric loading

Specific electric loading

It is defined as electric loading per meter of periphery, denoted by \bar{ac} .

$$\bar{ac} = \frac{Z I_z}{\Pi D}$$

$$\text{Or } Z I_z = \bar{ac} \Pi D$$

So put the above values equation (1) can be written as

$$Q = \frac{PN\phi Z}{60A} \times A I_z \times 10^{-3} \quad KW \quad \text{-----(2)}$$

$$Q = \frac{PN}{60A} \phi \times A \times Z I_z \times 10^{-3} \quad KW$$

$$Q = \frac{PN}{60A} \left(\bar{B} \times \frac{\Pi D}{P} \times L \right) \times A \times \left(\bar{ac} \Pi D \right) \times 10^{-3} \quad KW$$

$$Q = \left(16.4 \times 10^{-5} \bar{B} \bar{ac} \right) D^2 L N \quad KW$$

$$\boxed{Q = C D^2 L N \quad KW}$$

Where

$$C = \text{Output Co-efficient} = 16.4 \times 10^{-5} \bar{B} \bar{ac}$$

D = Inner diameter of stator

L = Length of the IM

$$\bar{B} = 0.45 \text{ to } 0.75 \text{ T}$$

$\bar{ac} = 15000$ to 20000 ac/m	for 4-20	Kw
$= 25000$ to 31000 ac/m	for 50-200	Kw
$= 36000$ to 50000 ac/m	for >500	Kw

DESIGN PROCEDURE OF DC MACHIN:

1. Estimation of main dimensions (D, L)

We know

$$D^2 L = \frac{Q}{CN} \text{ ----- (1)}$$

Where $C = \text{Output Co-efficient} = 16.4 \times 10^{-5} \bar{B} \bar{ac}$

$$\left\{ \begin{array}{l} \frac{L}{\tau_p} = 0.45 \rightarrow 1.1 \quad : \text{Wide range} \\ = 1 \rightarrow 1.5 \quad : \text{Economical Design} \end{array} \right\} \text{----- (2)}$$

Note: Selection of no of poles

f = frequency of supply = $\frac{PN}{120} = 25-50$ Hz, from here calculate the value of no of poles.

Solving equation (1) & (2) we can find out D & L.

2. Check for D & L

Peripheral speed

$$V_p = \frac{\pi DN}{60} < 60 \text{ m/sec}$$

3. Length of air gap

$$\delta = (4 \rightarrow 5) \frac{D}{P}$$

4. Find effective length

Ventilating ducts are required when $L > 12$ Cm and for every 7 to 8 Cm, we provide 0.8 cm ventilating duct.

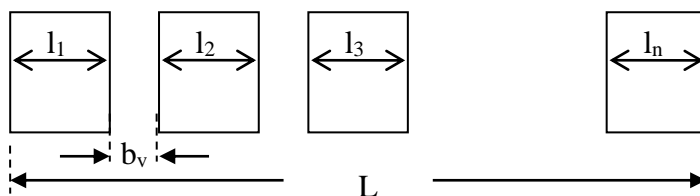
Generally

$$l_1 = l_2 = l_3 = \dots = l_n$$

Let

$n_v =$ No of ventilating ducts

$b_v =$ Width of one ventilating duct



Gross Iron length

$$l = l_1 + l_2 + l_3 + \dots + l_n$$

Actual Iron length

$$l_i = K_i * l$$

Where $K_i =$ Stacking factor

$$=0.90 \text{ to } 0.92$$

Overall length

$$L = 1 + n_v \cdot b_v$$

Effective length

$$L_e = L - n_v \times b'_v$$

Where $b'_v = b_v \frac{5}{5 + \frac{b_v}{\delta}}$ = Effective width of ventilating duct ($< b_v$ due to fringing)

5. Design of winding

$$E_g = \frac{PN\phi Z}{60A} \Rightarrow Z = \frac{60A}{PN\phi} E_g$$

$$\phi = \bar{B} \times \tau_p \times L = \bar{B} \times \frac{\Pi D}{P} \times L$$

Armature slots

$$S = \frac{\Pi D}{\tau_{Sg}}$$

$$\tau_{Sg} = \text{Slot pitch} = 15 \rightarrow 20 \text{ mm}$$

No of conductors per slot

$$N_c = \frac{Z}{S}$$

N_c Must be an integer and divisible by 2 for double layer windings. If not an integer make it integer and hence find the corrected value of N_c that is $N_{C,corrected}$. Also find out the corrected values of followings

$$Z_{corrected}$$

$$\phi_{corrected}$$

$$\bar{B}_{corrected}$$

Armature current

$$I_a = \frac{Q \times 10^3}{E_g}$$

X-sectional area of conductor

$$F_c = \frac{I_a}{\delta(2 \rightarrow 2.5)A/mm^2}$$

6. Design of commutator

No of commutator segments

$$C = \text{No of coils}$$

No of conductors in parallel path

$$= \frac{Z}{A}$$

No of turns

$$= \frac{1 Z}{2 A}$$

$$\text{No of coils} = \frac{\text{Total No of turns in parallel path}}{\text{Turns/Coil}}$$

Width of each commutator segments

=3 to 4 mm

Mica insulation

=0.8 mm

Dia of commutator

$D_C = (0.6 \text{ to } 0.8) D$

The voltage per commutator segment should be between 25 to 30 volts.

7. Find Characteristics

Find out core loss and Cu loss and efficiency

$$\eta = \frac{\text{O/p power}}{\text{O/p power} + \text{Core loss} + \text{Iron loss}}$$

Choice of Pole:

- In ac machines, number of poles are fixed by the relation $N=120f/P$.
- But in DC machines theoretically any number of poles can be used
- However there is a small range of number of poles which are economically suitable
- Consider that main dimension and specific loading i.e. D, L, B_{av} , ac are fixed and that the number of poles may be varied.
- It depends on a number of factors:
 1. Frequency: frequency of flux reversal -> should be less
 2. Weight of Iron parts of the machine
 3. Filed magnets
 4. Weight of copper
 5. Length of commutator
 6. Flash over between brushes
 7. Distortion of field from
 8. Labour charges